## Data Sheet | Force Transducer Series DR



Threaded version
1.25 kN - 1.25 MN


Flange version
50 kN - 2.5 MN

## Applications | Key Facts

Dynamic force applications: materials testing | component and structural testing | industrial quality and process control

- Dynamic tensile and compressive forces
- Flat, robust design | low mass and very high resonance frequency
- Accuracy class: 0.03-0.06
- Permissible oscillation stress $100 \%$
- Force transmission via flange or thread
- Standard variants or configurable variants for maximum flexibility


## Options | Accessories

- Optionally with 2 integrated MEMS acceleration sensors
- Optional second axial measuring circuit for redundancy
- Extensive electrical connection options
- Extensive mechanical accessories | Special solutions (on request)
- Bending moment measuring circuits $\mathrm{Mx}, \mathrm{My}$ (on request)
- UNF connection threads (on request)
- With additional plug protection (on request)
- Special versions also in small quantities (on request)

Technical Data | Threaded Version | 1.25-1.25 MN

|  | Nominal force compression/tension | $\pm F_{\text {nom }}$ | kN | 1.25 | 2.5 | 5 | 12.5 | 25 | 50 | 125 | 250 | 500 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Accuracy class |  |  |  | 0.03 |  | 0.04 |  |  |  |  | 0.06 |
|  | Linearity error | $d_{l i n}$ | \% |  | 0.03 |  | 0.04 |  |  |  |  | 0.06 |
|  | Hysteresis | $h$ | \% |  | 0.03 |  | 0.04 |  |  | 0.05 |  | 0.06 |
|  | Repeatability (f.s.) |  | \% |  | 0.025 |  |  |  |  |  |  |  |
|  | Zero error | $f_{0}$ | \% |  | 0.01 |  |  |  |  |  |  |  |
|  | Creep |  | \% |  | 0.025 |  |  |  |  |  |  |  |
|  | Temperature effect on characteristic value per 10 K | $T K_{C}$ | \%/10 K |  | 0.015 |  |  |  |  |  |  |  |
| $\begin{aligned} & \pi \\ & 0 \\ & 0 \end{aligned}$ | Temperature effect on zero signal per 10 K | $T K_{0}$ | \%/10 K |  | 0.015 |  |  |  |  |  |  |  |
| . | Eccentricity effect |  | \%/mm |  | $<0.01$ |  |  |  |  |  |  |  |
| $\begin{aligned} & 00 \\ & 0 \\ & \hline 0 \end{aligned}$ | Bending moment effect |  | \%/N•m |  | $<0.01$ |  |  |  |  |  |  |  |
| $\frac{2}{2}$ | Characteristic value difference, tension/compression force | $d_{Z D}$ | \% |  | 0.1 |  |  |  |  |  |  |  |
|  | Rated characteristic value | $C_{\text {nom }}$ | $\mathrm{mV} / \mathrm{V}$ |  | 1 |  | 2 |  |  |  |  |  |
|  | Characteristic value tolerance | $d_{c}$ | \% |  | 0.25 |  |  |  |  |  |  |  |
|  | Zero signal deviation | $d_{S, 0}$ | \% |  | 1 |  |  |  |  |  |  |  |
| $$ | Input resistance | $R_{e}$ | $\Omega$ |  | 350 |  |  |  |  |  |  |  |
|  | Output resistance | $R_{a}$ | $\Omega$ |  | 280-360 |  |  |  |  |  |  |  |
|  | Insulation resistance | $R_{\text {is }}$ | $\Omega$ |  | $>10^{9}$ |  |  |  |  |  |  |  |
| - | Operating range of excitation voltage | $B_{U, G}$ | V |  | 0.5-12 |  |  |  |  |  |  |  |
| - | Protection (DIN EN 60529) |  |  |  | 67 |  |  |  |  |  |  |  |

Technical Data | Threaded Version | 1.25-1.25 MN

|  | Nominal forcecompression/tension | $\pm F_{\text {nom }}$ | kN | 1.25 | 2.5 | 5 | 12.5 | 25 | 50 | 125 | 250 | 500 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Rated Displacement | $S_{\text {nom }}$ | mm | 0.02 |  |  | 0.03 |  |  | 0.04 | 0.05 | 0.06 |
|  | Spring rigidity | $c_{a x}$ | kN/mm | 62.5 | 125 | 250 | 415 | 830 | 1650 | 3125 | 5000 | 8300 |
| $\bigcirc$ | Mass | $m$ | kg | 0.5 |  | 1.3 |  |  | 5 |  | 11 | 28 |
| $\bigcirc$ | Proportionate moving mass | $m_{\text {mess }}$ | kg | 0.09 |  |  | 0.25 |  | 1.1 |  | 3.3 | 6.3 |
| $\frac{5}{0}$ | Fundamental resonant frequency | $f_{G}$ | kHz | 4.5 | 5.9 | 9.3 | 6.6 | 9.2 | 6.5 | 8.1 | 6.6 | 6.1 |
| $\pm$ | Permissible oscillation stress |  | \% | 100 |  |  |  |  |  |  |  |  |
|  | Force limit |  | \% | 230 |  |  |  |  |  |  |  |  |
|  | Breaking force |  | \% | >400 |  |  |  |  |  |  |  |  |
|  | Lateral force limit |  | \% | 100 |  |  |  |  |  |  |  |  |
|  | Permissible eccentricity | $e_{G}$ | mm | 25 |  |  |  |  |  |  | 20 |  |
| ¢ | Bending moment limit | $M_{\text {bzul }}$ | $N \cdot m$ | 40 | 80 | 140 | 330 | 635 | 1750 | 4500 | 9000 | 20000 |
|  | Rated temperature range | $B_{T, n o m}$ | ${ }^{\circ} \mathrm{C}$ | $-10-+45$ |  |  |  |  |  |  |  |  |
|  | Operating temperature range | $B_{T, G}$ | ${ }^{\circ} \mathrm{C}$ | $-30-+85$ |  |  |  |  |  |  |  |  |

## Technical Data | Flange Version | 50 kN - 2.5 MN



## Technical Data | Flange Version | 50 kN - 2.5 MN



## Cable Connection | All Variants


cable connector: - appliance inlet:


| Connection | Wire color | Pin |  |
| :--- | :---: | :---: | :---: |
| Supply voltage (+) | $\mathrm{U}_{\text {in+ }}$ | blue | A |
| Supply voltage (-) | $\mathrm{U}_{\text {in- }}$ | black | D |
| Measurement signal (+) | $\mathrm{U}_{\text {out+ }}$ | white | B |
| Measurement signal (-) | $\mathrm{U}_{\text {out- }}$ | red | C |
| Sense (+) | Sense+ | green | F |
| Sense (-) | Sense- | grey | E |
| Shielding |  |  | Housing |

1) View too weldingside
2) Female Amphenol typ: MIL-C-26482 series 1 ; bayonet catch


Pluggable cable connection

- Suitable measuring cable: S-CAB-SMC-B-5M-F or C-CAB-...


## Double Measuring Bridge | $\mathbf{~} \mathbf{2 . 5} \mathbf{~ k N}$

In the version with double measuring bridge (available as configurable variant), a second metrological equivalent signal is led out via an additional connector. The technical data for both measuring circuits apply equally.


## - Standard force transducer series DR

Single measuring bridge $\mid 1 \times$ bayonet connection | threaded version


- Configurable force transducer series DR

Single measuring bridge $\mid 2 \times$ MEMS
accelerometers $\mid 2 \times$ bayonet connection | threaded version


- Configurable force transducer series DR

Single measuring bridge $\mid 2 \times$ MEMS
accelerometers $\mid 3 \times$ bayonet connection | threaded version

## Cable Connection | MEMS Acceleration Sensor



1) View too weldingside
2) Female Amphenol typ: MIL-C-26482 series 1 ; bayonet catch


Pluggable cable connection | suitable measuring cable: S-CAB-SMC-B-5M-F

## Technical Data | MEMS Acceleration Sensor

| Typ |  | 1 | II |
| :---: | :---: | :---: | :---: |
| Rated acceleration | $g$ | 19 | 50 |
| Rated sensitivity at 5 V | $\mathrm{mV} / \mathrm{g}$ | $57 \pm 10$ | $40 \pm 2$ (ratiometric) |
| Static output voltage at 0 g | $\mathrm{V}_{\mathrm{DC}}$ | $1.5 \pm 0.25$ | $2.5 \pm 0.25$ |
| Typical bandwidth | kHz | 1.6 | 11 |
| Excitation voltage | $\mathrm{V}_{\text {DC }}$ | $(5 \pm 0.25)$ |  |
| Linearity error | \% | 0.3 | 0.1 |
| Resonant frequency | kHz | 5.5 | 21 |



## Dimensions | Threaded Version | 1.25 - 1.25 kN



| Nominal force compression/tension | $\pm F_{\text {nom }}$ | kN | 1.25 | 2.5 | 5 | 12.5 | 25 | 50 | 125 | 250 | 500 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Bore | $\emptyset B_{1}$ | mm | 7.1 |  |  |  |  | 10.4 |  | 13.5 | 16.8 |
| Thread | $\emptyset T_{1}$ | mm | M16x2-4H |  |  |  |  | M $33 \times 2-4 \mathrm{H}$ |  | $\mathrm{M} 42 \times 2-4 \mathrm{H}$ | M $72 \times 2-4 \mathrm{H}$ |
| Diameter | $\varnothing D_{1}$ | mm | 104.8-0.1 |  |  |  |  | 153.9-0.1 |  | 203,2-0.1 | 279-0.1 |
| Diameter | $\emptyset D_{2}$ | mm | 101.6+0.1 |  |  |  |  | 149+0.1 |  | 198.1+0.1 | 269.2+0.1 |
| Diameter | $\varnothing D_{3}$ | mm | 79.2-0.1 |  |  |  |  | 115-0.1 |  | 146-0.1 | 188-0.1 |
| Diameter | $\emptyset D_{4}$ | mm | 74.7+0.1 |  |  |  |  | 108+0.1 |  | $138.9+0.1$ | 172.1+0.1 |
| Diameter | $\varnothing D_{5}$ | mm | 34+0.1 |  |  |  |  | 61.2-0.1 | 67.3-0.1 | 95.2-0.1 | 122.2-0.1 |
| Diameter | $\varnothing D_{6}$ | mm | $16.5 \mathrm{H8}$ |  |  |  |  | $33.5 \mathrm{H8}$ |  | 43н8 | 73н8 |
| Pitch circle diameter | $\emptyset P_{1}$ | mm | $88.9 \pm 0.1$ |  |  |  |  | $130.3 \pm 0.1$ |  | $165.1 \pm 0.1$ | $229 \pm 0.1$ |
| Height | $H_{1}$ | mm | 34.9-0.1 |  |  |  |  | 44.5-0.1 |  | 63.5-0.1 | 88.9-0.1 |
| Height | $\mathrm{H}_{2}$ | mm | 3.2 |  |  |  |  | 3.1 |  | 6.3 | 12.7 |
| Height | $\mathrm{H}_{3}$ | mm | 15.9 |  |  |  |  | 20.7 |  | 28.6 | 38.1 |
| Height | $\mathrm{H}_{4}$ | mm | 0.5 |  |  |  |  |  |  |  | 0.8 |
| Height | $H_{5}$ | mm | 0.5 |  |  |  |  |  |  | 1 |  |
| Height | $H_{6}$ | mm | 3.4 |  |  |  |  | 3.5 |  | 3 |  |
| Angle | $a_{1}$ |  | $22.5{ }^{\circ}$ |  |  |  |  | $15^{\circ}$ |  | $11.25^{\circ}$ |  |
| Angle | $a_{2}$ |  | $8 \times 45^{\circ}$ |  |  |  |  | $12 \times 30^{\circ}$ |  | $16 \times 22.5^{\circ}$ |  |

## Dimensions | Flange Version | $\mathbf{5 0} \mathbf{~ k N} \mathbf{- 2 , 5} \mathbf{~ M N}$



| Nominal force compression/tension | $\pm F_{\text {norm }}$ | kN | 50125 | 250 | 500 | 1000 | 1500 | 2000 | 2500 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Bore | $\varnothing B_{1}$ | mm | 10.5 | 13 | 17.5 | 22 | 26 | 33 | 30 |
| Bore | $\emptyset B_{2}$ | mm | 10H7 |  |  |  |  |  |  |
| Bore | $\emptyset B_{3}$ | mm | 10.5 | 17 | 17.5 | 26 |  | 33 |  |
| Bore | $\emptyset B_{4}$ | mm | $10 \mathrm{H7}$ | 16H7 |  |  |  |  |  |
| Diameter | $\varnothing D_{1}$ | mm | 153.9 | 203.2 | 279 | 304.8 | 393.7 | 480 | 520.7 |
| Diameter | $\theta D_{2}$ | mm | 108H8 | 138.9 $\mathrm{H8}$ | $172.1 \mathrm{H8}$ | 195H8 | 254.4H8 | $310 \mathrm{H8}$ | 340H8 |
| Diameter | $\varnothing D_{3}$ | mm | 61.2h9 | 95.5n9 | 122.2h9 | 144.3n9 | 196.9h9 | 232h9 | 267.9h9 |
| Pitch circle diameter | $\emptyset P_{1}$ | mm | $130.3 \pm 0.1$ | $165.1 \pm 0.1$ | $229 \pm 0.1$ | 241.3 $\ddagger 0.1$ | $322.1 \pm 0.1$ | $385 \pm 0.2$ | $419.1 \pm 0.2$ |
| Pitch circle diameter | $\emptyset P_{2}$ | mm | $45 \pm 0.1$ | $71 \pm 0.1$ |  | $105 \pm 0.1$ | 150 $\pm 0.1$ | $180 \pm 0.2$ | $215 \pm 0.2$ |
| Thread | $T_{1}$ |  | - |  | M12 |  |  |  |  |
| Height | $H_{1}$ | mm | 44.5-0.1 | 63.5-0.1 | 88.9-0.1 | 114.3-0.1 | 139.7-0.1 | 155-0.1 | 158.8-0.1 |
| Height | $\mathrm{H}_{2}$ | mm | 3.1 | 6.3 | 12.7 | 6.3 | 12.7 | 6.3 |  |
| Height | $\mathrm{H}_{3}$ | mm | 20.5 | 28.6 | 37.9 | 54 | 63.5 | 74.5 |  |
| Height | $\mathrm{H}_{4}$ | mm | 17 |  |  |  |  |  |  |
| Height | $H_{5}$ | mm | 0.5 |  | 1 |  |  |  |  |
| Height | $H_{6}$ | mm | 10 | 20 |  |  |  |  |  |
| Height | $\mathrm{H}_{7}$ | mm | - |  | 24 |  |  |  |  |

## Dimensions | Flange Version | 50 kN - 2,5 MN

| Nominal force compression/tension | $\pm F_{\text {norm }}$ | kN | $50 \quad 125$ | 250500 | 1000 | 15002000 | 2500 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Angle | $a_{1}$ |  | $15^{\circ}$ | $11.25^{\circ}$ | $9^{\circ}$ | $7.5^{\circ}$ | $6.43^{\circ}$ |
| Angle | $a_{2}$ |  | $15^{\circ}$ | $11.25^{\circ}$ | $9^{\circ}$ | $7.5^{\circ}$ | $6.43{ }^{\circ}$ |
| Angle | $a_{3}$ |  | $12 \times 30^{\circ}$ | $16 \times 22.5^{\circ}$ | $20 \times 18^{\circ}$ | $24 \times 15^{\circ}$ | $28 \times 12.86^{\circ}$ |
| Angle | $a_{4}$ |  |  | $56.25^{\circ}$ | $63^{\circ}$ | $52.5{ }^{\circ}$ | $57.8{ }^{\circ}$ |
| Angle | $a_{5}$ |  | $15^{\circ}$ | $11.25^{\circ}$ | $9^{\circ}$ | $7.5^{\circ}$ | $6.43^{\circ}$ |
| Angle | $a_{6}$ |  |  | $8 \times 45^{\circ}$ |  | $12 \times 30^{\circ}$ | $14 \times 25.71^{\circ}$ |

## Order Numbers | Standard Variants

Force transducer Series DR | standard variants

| Nominal |  | Description | Figure (similiar) | Order number |
| :---: | :---: | :---: | :---: | :---: |
| Force | Signal |  |  |  |
| Standard force transducer series DR \| threaded version |  |  |  |  |
| 1.25 kN | $1 \mathrm{mV} / \mathrm{V}$ | Force transducer series DR $\|1.25 \mathrm{kN}\|$ threaded version |  | S-DR-1K25-T |
| 2.5 kN | $1 \mathrm{mV} / \mathrm{V}$ | Force transducer series DR $\|2.5 \mathrm{kN}\|$ threaded version |  | S-DR-2K50-T |
| 5 kN | $1 \mathrm{mV} / \mathrm{V}$ | Force transducer series DR $\|5 \mathrm{kN}\|$ threaded version |  | S-DR-5K00-T |
| 12.5 kN | $2 \mathrm{mV} / \mathrm{V}$ | Force transducer series DR $\|12.5 \mathrm{kN}\|$ threaded version |  | S-DR-12K5-T |
| 25 kN | $2 \mathrm{mV} / \mathrm{V}$ | Force transducer series DR \| 25 kN | threaded version |  | S-DR-25K0-T |
| 50 kN | $2 \mathrm{mV} / \mathrm{V}$ | Force transducer series DR \| 50 kN | threaded version |  | S-DR-50K0-T |
| 125 kN | $2 \mathrm{mV} / \mathrm{V}$ | Force transducer series DR $\|125 \mathrm{kN}\|$ threaded version |  | S-DR-125K-T |
| 250 kN | $2 \mathrm{mV} / \mathrm{V}$ | Force transducer series DR \| $250 \mathrm{kN} \mid$ threaded version |  | S-DR-250K-T |
| 500 kN | $2 \mathrm{mV} / \mathrm{V}$ | Force transducer series DR \| 500 kN | threaded version |  | S-DR-500K-T |
| Standard force transducer series DR \| flange version |  |  |  |  |
| 50 kN | $2 \mathrm{mV} / \mathrm{V}$ | Force transducer series DR \| 50 kN | flange version |  | S-DR-50K0-F |
| 125 kN | $2 \mathrm{mV} / \mathrm{V}$ | Force transducer series DR \| 125 kN | flange version |  | S-DR-125K-F |
| 250 kN | $2 \mathrm{mV} / \mathrm{V}$ | Force transducer series DR \| 250 kN | flange version |  | S-DR-250K-F |
| 500 kN | $2 \mathrm{mV} / \mathrm{V}$ | Force transducer series DR \| 500 kN | flange version |  | S-DR-500K-F |

[^0]
## Order Numbers | Configurable Variants

Force transducer Series DR | configurable variants

| Item | Code | Description |
| :---: | :---: | :---: |
| Force Transducer Series DR | C-DR | Configurable force transducer series DR |
| Nominal Force | 1K25 | 1.25 kN |
|  | 2K50 | 2.5 kN |
|  | 5K00 | 5 kN |
|  | 12K5 | 12.5 kN |
|  | 15K0 | 15 kN |
|  | 25K0 | 25 kN |
|  | 50K0 | 50 kN |
|  | 100K | 100 kN |
|  | 125K | 125 kN |
|  | 250K | 250 kN |
|  | 500K | 500 kN |
|  | 1M00 | 1 MN |
|  | 1M50 | 1.5 MN |
|  | 2M00 | 2 MN |
|  | 2M50 | 2.5 MN |
| Mechanical design | F | Flange |
|  | T | Thread |
| Mounting | M | Metric |
|  | F | Flange |
| Mounting adapter | N | No mounting parts |
|  | Y | With mounting parts |
| Plug protection | N | No plug protection |
| Nominal sensitivity | 2.0 | $2 \mathrm{mV} / \mathrm{V}$ |
|  | 1.0 | $1 \mathrm{mV} / \mathrm{V}$ |
| Single or double measuring bridge | SB | Single bridge |
|  | DB | Double bridge |
| Bending moment measuring circuits Mx, My | NO | No bending moment measuring circuits Mx, My |
| Accelerometers | NO | No accelerometers |
|  | AC | With 2 integrated accelerometers |
| Temperature range | S | Standard temperatur range $\mid+10^{\circ} \mathrm{C}-+45^{\circ} \mathrm{C}$ |
| Electrical transducer connection (for all selected measuring circuits) | P | Bayonet connector socket(s) \| 6-pole |
| Cable connection type (for all selected measuring circuits) | P | Bayonette connector(s) on all selected measuring circuits \| no permanently mounted measuring cable(s) |

Order-Example

| C-D R | 125K | T | M | Y | N | 2 | SB | NO | A C |  | S | - | P |  | P |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 125 kN | Threaded version | M etric | with bottom plate | no plug protection | $\begin{array}{\|l} \hline 2 \\ \mathrm{mV} / \mathrm{l} \\ \mathrm{~V} \\ \hline \end{array}$ | single bridge | No bending moment circuits Mx, My | with 2 integrated accelerometers |  | standard temperatur e range |  | Bayonet socket(s) |  | Bayonet socket(s) |

## Order Numbers | Configurable Variants | Glossary

| Item | Description |
| :---: | :---: |
| Mechanical design | The series DR force transducer has different mechanical interfaces depending on the nominal load. $\begin{aligned} & \mathrm{F}=\text { flange version \| nominal load: } 50 \mathrm{kN}-2.5 \mathrm{MN} \\ & \mathrm{~T}=\text { Threaded version } \mid \text { Nominal load: } 1.25 \mathrm{kN}-1.25 \mathrm{MN} \end{aligned}$ |
| Mounting | The DR series force transducer can be equipped and fitted in the threaded version with both metric and inch threads. Both variants are identical in construction. UNF threads are available on request and in selected nominal loads. <br> Flange version <br> $\mathrm{F}=$ Flange mounting <br> Threaded version <br> M = Metric $\mid$ Standard <br> UNF thread on request and in selected nominal loads. |
| Mounting adapter | Depending on the nominal load, the force transducer series DR-T (threaded version) can be equipped with additional attachments. The attachments are all pre-assembled at the factory. <br> - Nominal load: 1.25-2.5 kN with base plate (aluminium) M16\|mounted <br> - Nominal load: 12.5-25 kN with base plate M16 (steel) \| mounted <br> - Nominal load: 50 kN with base plate M16 (steel) \| mounted <br> - Nominal load: 125 kN with base plate M33×2 (steel) \| mounted <br> - Nominal load: 250 kN with base plate M42×2 (steel) \| mounted <br> - Nominal load: 500 kN with base plate M72×2 (steel) \| mounted |
| Plug protection | In special cases it may be necessary to additionally equip the electrical connections on the force transducer series DR with a protective profile around the plug connection. Dimensions depending on nominal load and on request. |
| Nominal sensitivity | The DR series force transducer has the following nominal sensitivity depending on the nominal force. The permissible oscillation stress of $\pm 100 \%$ applies to all nominal forces. $\begin{aligned} & 1 \mathrm{mV} / \mathrm{V}=1.25-5 \mathrm{kN} \\ & 2 \mathrm{mV} / \mathrm{V}=>5 \mathrm{kN} \end{aligned}$ |
| Single or double measuring bridge | For redundancy reasons, it is necessary, for example in safety-relevant applications, to check the safetyrelevant integrity of the measuring signal by means of a second measuring bridge (functional redundancy in the same force transducer). Two force transducer output signals are processed and evaluated independently of each other via two separate measuring amplifier channels. This makes it possible to connect two measuring amplifiers with different characteristics (DC / TF). The second redundant measuring circuit, is characterised by no crosstalk between the channels at different carrier frequencies. <br> Notes: <br> The selection of a double measuring bridge affects the number of connection sockets. <br> The double measuring bridge can be selected from 2.5 kN (also applies to the combination with optional acceleration sensors). |
| Bending moment measuring circuits $\mathbf{M x}, \mathbf{M y}$ | The Series DR force transducer can be equipped with bending moment measuring circuits on request. The additional bending moment measuring circuits can be measured to control the horizontal bending moments Mx and My and can be provided as separate channels. <br> Notes: <br> The selection of bending moment measuring circuits affects the number of connection sockets. <br> The bending moment circuits can only be selected in combination with a single or double measuring bridge. A combination with accelerometers on request. |
| MEMS accelerometers | The Series DR force transducer can optionally be equipped with two integrated MEMS accelerometers. In this way, for example, the resulting inertial forces of the force measurement setup or the test stand setup can be determined easily and effectively during dynamic measurements. |
| Temperature range | $\mathrm{S}=$ Standard temperature range $-10^{\circ} \mathrm{C}-+45^{\circ} \mathrm{C}$ |

Note: Continued on next page

## Order Numbers | Configurable Variants | Glossary

| Item | Description |
| :--- | :--- |
| Electrical | The DR series force transducer can be configured with fixed bayonet connection sockets. The number of |
| connection | connection sockets results from the number of selected measuring bridges. <br> $\mathrm{P}=$ Bayonet connection socket(s) $\mid 6$-pole |
| Note: <br> Fixed measuring cables on request. |  |
| Cable connection <br> type | With pluggable Bayonet connection, no additional cable connection type is available. <br> P = Bayonet connection socket(s) selected $\mid$ no permanently mounted test lead(s). <br> Note: <br> Further options with measuring cables on request. |

Order-Example


## Order Numbers | Accessories

| Description | Order number |
| :---: | :---: |
| Measuring cable |  |
| Standard measuring cable \|grey $\|5 \mathrm{~m}\|$ shielded and twisted in pairs\| outer sheath $\varnothing 6.5$ mm \| 6-wire technology | transducer connection: Bayonet connector type MIL-C-26482 S | 6-pole | Cable end amplifier: open | S-CAB-SMC-B-5M-F |
| Configurable measuring cable type SMC, DMC, TMC, FMC \| in different lengths | with different connectors for amplifier connection | C-CAB-xxx-BA6S-xxx-xxxx |
| Series DR \| bottom plate for threaded version (1 piece) |  |
| Serie DR \| 1.25-5 kN | bottom plate | S-MA-DR-BP-01 |
| Serie DR \| $12.5-25 \mathrm{kN}$ \| bottom plate <br> Sr | S-MA-DR-BP-02 |
| Serie DR \| 50 kN | bottom plate | S-MA-DR-BP-03 |
| Serie DR \| 125 kN | bottom plate | S-MA-DR-BP-04 |
| Serie DR \| 250 kN | bottom plate | S-MA-DR-BP-05 |
| Serie DR \| 500 kN | bottom plate | S-MA-DR-BP-06 |
| Notes: <br> 1.25-5 kN \|material: aluminium <br> > 12.5 kN \| material: steel |  |
| Series DR \| bolt set outer hole circle for threaded version (1 set) |  |
| Serie DR \| $1.25-5 \mathrm{kN}$ \| bolt set outer hole circle $\mid 8 \mathrm{pcs}$. | S-MA-DR-BO-01 |
| Serie DR \| $12.5-25 \mathrm{kN} \mid$ bolt set outer hole circle $\mid 8$ pcs. | S-MA-DR-BO-02 |
| Serie DR \| 50-125 kN | bolt set outer hole circle 12 pcs . | S-MA-DR-BO-03 |
| Serie DR \| 250 kN | bolt set outer hole circle ${ }^{\text {a }} 12$ pcs. | S-MA-DR-BO-04 |
| Serie DR \| 500 kN | bolt set outer hole circle ${ }^{\text {l }} 16$ pcs. | S-MA-DR-BO-05 |
| Note: 1 set for mounting the bottom plate via outer hole circle threaded version |  |



## Configurable force transducer series DR

Single measuring bridge |MEMS accelerometers $\mid 2 x$ bayonet connection | threaded version | bottom plate pre-assembled


[^0]:    Note: all standard variants always (1) with metric thread (2) without mounting parts (3) no plug protection (4) single measuring bridge (5) no integrated accelerometers (6) standard temperature range (7) $1 x$ bayo net connection socket 6-pin | no measuring cables included

